# **Reparameterized Multi-Resolution Convolutions for Long** Sequence Modelling

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## Introduction

- Global convolutions have shown increasing promise as efficient general-purpose sequence models.
- However, training long convolutions is hard, and kernel parameterizations must learn long-range dependencies without overfitting.
- This work introduces reparameterized multi-resolution convolutions (MRConv), which uses structural reparameterization to combine a set of low-rank sub-kernels of increasing length.

# MRConv: Reparameterized Multi-Resolution Convolutions



**Low-Rank Kernel Parameterization** 



**Dilated Kernels** Variation on standard convolutional filters where p many zeros are padded between the elements of the kernel,

$$y[t] = (u * k_{dilated})[t] = \sum_{0}^{l-1} k[\tau]u[t - p\tau].$$
 (8)

### **Causal Structural Reparameterization**

We can merge multiple causal convolutions into one as

$$y[t] = \sum_{n=0}^{N-1} (u * k_n)[t] = \left(u * \left(\sum_{n=0}^{N-1} k_n\right)\right) [t] = (u * k_{rep})[t], \quad (1)$$

where  $k_n$  is the convolution kernel of the *n*th branch

**Causal Branch Addition with BatchNorm** When merging kernels of different lengths, normalization becomes crucial due to the impact of kernel size on the output statistics,

$$k_{rep} = \overline{\mathbf{BN}_0(k_0)} + \overline{\mathbf{BN}_1(k_1)},\tag{2}$$

**Causal Branch Addition with Linear Rescaling** When merging kernels of the same length, we use linear scaling allowing kernels to be reparameterized during training,

$$k_{rep} = \beta_0 \cdot k_0 + \beta_1 \cdot k_1. \tag{3}$$

#### **Multi-Resolution Convolutions**

 $\tau=0$ 

**Fourier Kernels** Complex kernels  $\hat{k} \in \mathbb{C}^{D \times L}$  parameterized in the Fourier domain as a small number *m* of low-frequency Fourier modes,

$$k_{fourier}[t] = IFFT[ZeroPad(\hat{k}, L - m)])[t].$$
(9)

**Sparse Kernels** We randomly sample kernel positions across the sequence length, where  $\delta_t \in \mathcal{T}$  is the Kronecker delta as,

$$k_{sparse}[t] = \delta_{t \in \mathcal{T}} \cdot k_t, \tag{10}$$

# Experiments

**Long Range Arena.** MRConv is competitive with other sub-quadratic complexity models, including SSMs and linear-time transformers.

Model (Input length)	ListOps (2,048)	Text (4,096)	Retrieval (4,000)	Image (1,024)	Pathfinder (1,024)	Path-X (16,384)	Avg.
Transformer	36.37	64.27	57.46	42.44	71.40	×	53.66
<i>Linear-Time Transformers:</i> MEGA-Chunk	58.76	90.19	90.97	85.80	94.41	93.81	85.66
State Space Models: S4D-LegS S4-LegS Liquid-S4 S5	60.47 59.60 <b>62.75</b> 62.15	86.18 86.82 89.02 89.31	89.46 90.90 91.20 <u>91.40</u>	88.19 88.65 <u>89.50</u> 88.00	93.06 94.20 94.8 95.33	91.95 96.35 96.66 <b>98.58</b>	84.89 86.09 87.32 <b>87.46</b>
Convolutional Models: CCNN Long Conv SGConv	43.60 62.2 61.45	84.08 <u>89.6</u> 89.20	- 91.3 91.11	88.90 87.0 87.97	91.51 93.2 <u>95.46</u>	<b>×</b> 96.0 <u>97.83</u>	- 86.6 87.17
MRConv	<u>62.40</u>	89.26	91.44	90.37	95.55	97.82	87.81

At each resolution *i*, we define a kernel  $k_i$  of length  $l_i = l_0 2^i$ . We define the set of normalized multi-resolution convolutions  $\tilde{c} \in \mathbb{R}^{N \times D \times L}$  as,

$$\tilde{\boldsymbol{c}} = [\mathbf{BN}_0(k_0 * u), \mathbf{BN}_1(k_1 * u), \cdots, \mathbf{BN}_{N-1}(k_{N-1} * u)].$$
(4)

The output  $y[t] \in \mathbb{R}^D$  at time step t is generated by computing a linear combination of the coefficients  $\tilde{c}[t]$  at time step t according to

$$y[t] = \boldsymbol{\alpha}^T \tilde{\boldsymbol{c}}[t], \tag{5}$$

where  $\alpha \in \mathbb{R}^{N \times D}$  is a learnable parameter. Applying  $\alpha$  across the sequence length we define the output  $y \in \mathbb{R}^{D \times L}$  as the summation

 $y = \alpha_0 BN_0(k_0 * u) + \alpha_1 BN_1(k_1 * u) + \dots + \alpha_{N-1} BN_{N-1}(k_{N-1} * u).$  (6) Applying causal structural reparameterization at inference, we can rewrite the above process as a single convolution,

$$y = u * (\alpha_0 \overline{\mathbf{BN}_0(k_0)} + \alpha_1 \overline{\mathbf{BN}_1(k_1)} + \dots + \alpha_{N-1} \overline{\mathbf{BN}_0(k_{N-1})}) = u * k_{rep},$$
(7)
eliminating the extra memory and computational cost of training with
extra convolutions.

**ImageNet Classification.** Using optimized CUDA kernels for 1D FFT convolutions, we close the gap between theoretical and empirical throughput.

