Reparameterized Multi-Resolution Convolutions for Long Sequence Modelling

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Introduction

- Global convolutions have shown increasing promise as efficient general-purpose sequence models.
- However, training long convolutions is hard, and kernel parameterizations must learn long-range dependencies without overfitting.
- This work introduces reparameterized multi-resolution convolutions (MRConv), which uses structural reparameterization to combine a set of low-rank sub-kernels of increasing length.

MRConv: Reparameterized Multi-Resolution Convolutions

Causal Structural Reparameterization

We can merge multiple causal convolutions into one as

$$
y[t] = \sum_{n=0}^{N-1} (u * k_n)[t] = \left(u * \left(\sum_{n=0}^{N-1} k_n\right)\right)[t] = (u * k_{rep})[t], \quad (1)
$$

where k_n is the convolution kernel of the *n*th branch

 $y = \alpha_0 BN_0(k_0 * u) + \alpha_1 BN_1(k_1 * u) + \cdots + \alpha_{N-1} BN_{N-1}(k_{N-1} * u)$. (6) Applying causal structural reparameterization at inference, we can rewrite the above process as a single convolution,

Causal Branch Addition with BatchNorm When merging kernels of different lengths, normalization becomes crucial due to the impact of kernel size on the output statistics,

$$
k_{rep} = \overline{\mathbf{BN}_0(k_0)} + \overline{\mathbf{BN}_1(k_1)},\tag{2}
$$

Dilated Kernels Variation on standard convolutional filters where p many zeros are padded between the elements of the kernel,

Causal Branch Addition with Linear Rescaling When merging kernels of the same length, we use linear scaling allowing kernels to be reparameterized during training,

Sparse Kernels We randomly sample kernel positions across the sequence length, where $\delta_t \in \mathcal{T}$ is the Kronecker delta as,

$$
k_{rep} = \beta_0 \cdot k_0 + \beta_1 \cdot k_1. \tag{3}
$$

Multi-Resolution Convolutions

 $\tau = 0$

Fourier Kernels Complex kernels $\hat{k} \in \mathbb{C}^{D \times L}$ parameterized in the Fourier domain as a small number m of low-frequency Fourier modes,

Long Range Arena. MRConv is competitive with other sub-quadratic complexity models, including SSMs and linear-time transformers.

$$
\tilde{c} = [BN_0(k_0 * u), BN_1(k_1 * u), \cdots, BN_{N-1}(k_{N-1} * u)].
$$
 (4)

The output $y[t] \in \mathbb{R}^D$ at time step t is generated by computing a linear combination of the coefficients $\tilde{c}[t]$ at time step t according to

$$
y[t] = \boldsymbol{\alpha}^T \tilde{\boldsymbol{c}}[t],\tag{5}
$$

where $\boldsymbol{\alpha} \in \mathbb{R}^{N \times D}$ is a learnable parameter. Applying $\boldsymbol{\alpha}$ across the sequence length we define the output $y \in \mathbb{R}^{D \times L}$ as the summation

$$
y = u * (\alpha_0 \overline{BN_0(k_0)} + \alpha_1 \overline{BN_1(k_1)} + \dots + \alpha_{N-1} \overline{BN_0(k_{N-1})}) = u * k_{rep},
$$

(7)
eliminating the extra memory and computational cost of training with
extra convolutions.

Low-Rank Kernel Parameterization

$$
y[t] = (u * k_{dilated})[t] = \sum_{0}^{l-1} k[\tau]u[t - p\tau]. \tag{8}
$$

$$
k_{fourier}[t] = \text{IFFT}[\text{ZeroPad}(\hat{k}, L - m)])[t]. \tag{9}
$$

$$
k_{sparse}[t] = \delta_{t \in \mathcal{T}} \cdot k_t,
$$
\n(10)

Experiments

At each resolution *i*, we define a kernel k_i of length $l_i = l_0 2^i$. We define the set of normalized multi-resolution convolutions $\tilde{c} \in \mathbb{R}^{N \times D \times L}$ as,

ImageNet Classification. Using optimized CUDA kernels for 1D FFT convolutions, we close the gap between theoretical and empirical throughput.

